

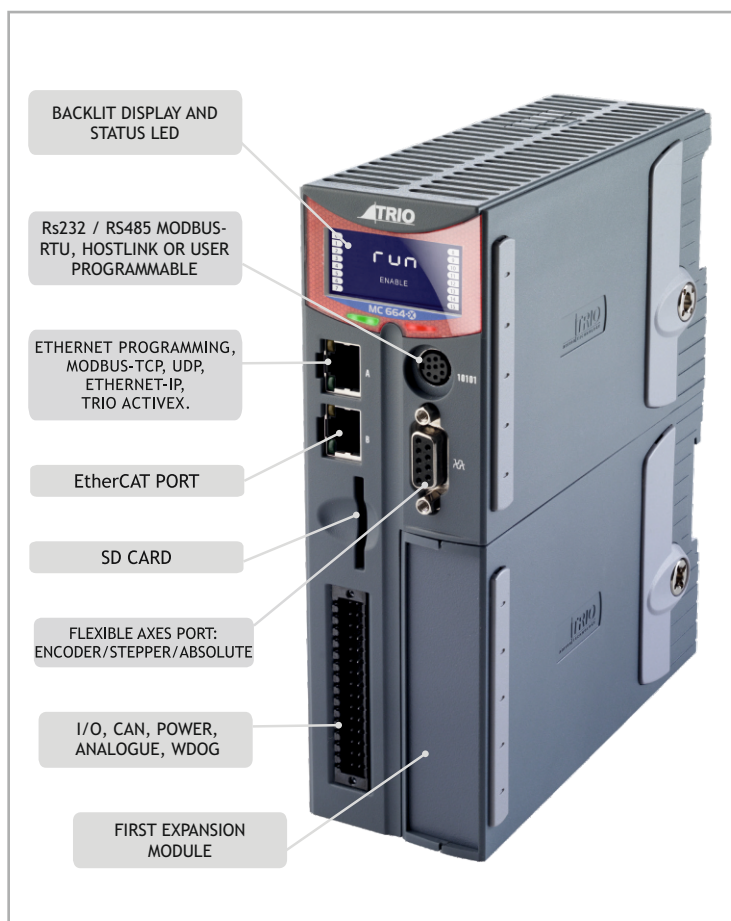
MC664X *Quad Core 128 Axis EtherCAT[®] Coordinator*

INTRODUCTION

The MC664X is a very performing flexible EtherCAT Motion Coordinator which perfectly fits the R.T.A. EtherCAT motion control solution (servos and steppers).

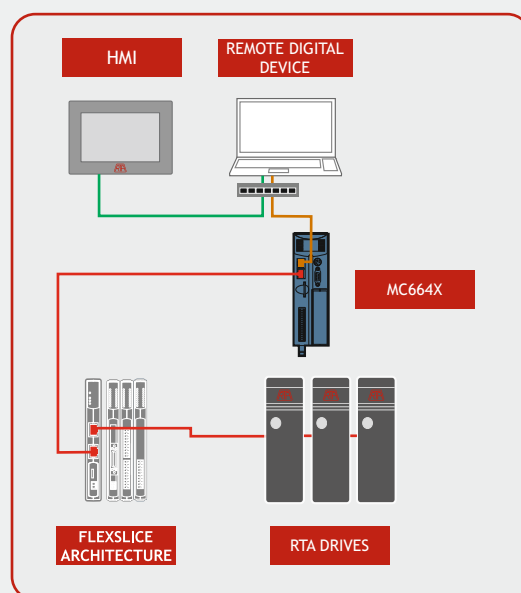
HIGHLIGHTS

- High performance Motion Coordinator for driving servo and stepper drives via EtherCAT bus.
- Able to manage up to 128 axes (64 stepper/servo and 64 virtual), 1024 digital inputs and outputs and 32 analogue inputs and analog outputs.
- Precise 64 bit Motion Calculations with Quad Core Cortex A9 1GHz Processor for multiple simultaneous robotic transformations.
- Ideal for ultra-precise axes count machines or robotic applications.
- Expansions modules available for managing step & dir analogue signals and encoder feedback.



SPECIFICATIONS

- Multitasking Operating System
- Comprehensive Motion Library
- TrioBasic Motion Language
- IEC61131-3 Programming
- TS SERIES HMI Support
- Robotic Functions (licensed separately)
- Multi-protocol Communications Support



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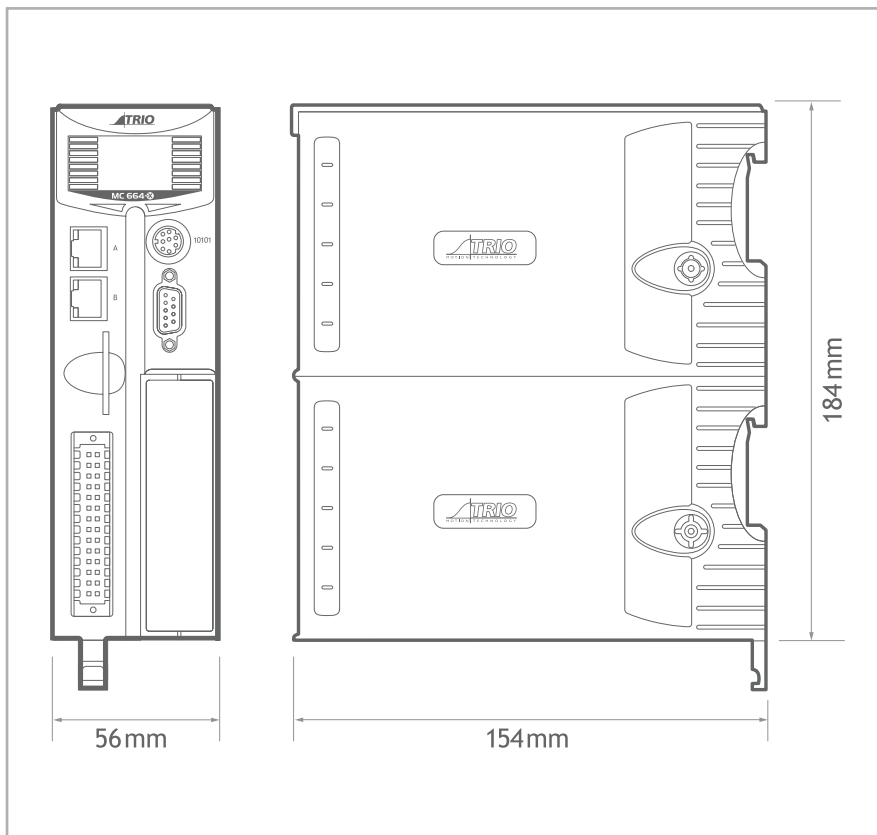
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TECHNICAL FEATURES

- Up to 128 Axes - Stepper / Servo Axes
- Precise 64 bit Motion calculations with Quad Core Cortex A9 1GHz Processor
- Dedicated communications Core
- Built-in EtherCAT port
- Built-in Ethernet interface / Ethernet-IP / Modbus TCP
- Anybus-CC module for flexible factory comms including Profinet/Profibus, Sercos II, SLM and RTE X
- Multi-tasking TRIO BASIC programming
- SD memory card slot
- CANopen I/O expansion
- Backlit LCD display



MECHANICAL DIMENSIONS



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